

a source of drive current for causing relative rotation between said windings and said magnet; and

an actuator combined with the motor and comprising a source of actuator current energizing said windings to generate a radial force which stabilizes the position of said spin axis and dampens movements of said rotor and disc including first and second probes associated with said rotor to measure a gyroscopic motion of said rotor of said shaft, ^{where on the} output of said probes ^{is} being processed to establish a signal applied to energize said first and second phase windings and stabilize said system.

73. (Amended) An apparatus as claimed in claim 72 including means for adjusting the direction of said correction force relative to a reference direction corresponding to the position of said probes.

74. (Amended) An apparatus as claimed in claim 73 including means for modifying the magnitude of said current applied to said first and second phases to adjust the magnitude of the correction force applied to said rotor.

75. (Amended) An apparatus as claimed in claim 74 including a comb filter responsive to the output of said probe to separate components that are synchronous with the speed of said motor of said rotating system from components that are not synchronous with said motor speed and represent oscillatory movements of said rotor to be dampened.

76. (Amended) Apparatus as claimed in claim 75 wherein said actuator current and said drive current are separately applied in time to said windings.

77. (Amended) Apparatus as claimed in claim 75 wherein said actuator current and said drive current are simultaneously applied to said windings.

78. (Amended) An apparatus as claimed in claim 72 wherein said motor has a slotless winding, and said windings of said actuator are concentric but placed in the same airgap between a core and the rotating magnets of said motor.

81. (Amended) An apparatus for stabilizing the spin axis of a rotating system comprising a disc drive, said rotating system comprising:

a rotor carrying an inertial load comprising at least one disc and bearing means to support said rotor and said disc about said spin axis, and

motor means to cause rotation of said rotor about said spin axis comprising:

a first set of windings;

a source of drive current for causing relative rotation between said windings and said magnet; and

an actuator combined with the motor and comprising a source of actuator current energizing said windings to generate a radial force which stabilizes the position of said spin axis and dampens movements of said rotor and disc further comprising;

means for sensing movements of said rotor;

comb means for separating non-repeating movements from repeating movements of said rotor;

said actuator being responsive to said comb means to stabilize said rotor.

82. (Amended) An apparatus as claimed in claim 80 wherein said actuator comprises first and second phase windings, which are separately wound and separately energized to generate two radial forces in quadrature.

83. (Amended) An apparatus as claimed in claim 80 comprising means for generating a signal defining each of said currents having first and second input signals representing components of said radial force to be generated, and a third input representing motor position;

memory means addressed with an argument of a function based on said rotor position for providing a trigonometric function based output based on said position; and

multiplier means responsive to said trigonometric function based output signal and said first and second input signals representing components of said radial force to generate elements of a said signal defining said currents.

84. (Amended) An apparatus as claimed in claim 80 wherein said multiplier means comprises a digital/analog converter having said trigonometric based output signals as one input and one of said first and second signals representing said radial force as another input.

85. (Amended) An apparatus as claimed in claim 80 including means for regularly resetting said signal generating means responsive to a motor driven pulse so that reset is proportional to motor rotational speed.

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86. (Amended) An apparatus as claimed in claim 80 including a circuit for incorporating an adjustable phase delay into said means for generating a current defining signal.

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